



## A Novel Approach for a Hostile Arms Fire Sensor

Joseph Rudy Montoya, PhD and Jorge Melchor  
US Army Research Laboratory-SLAD  
White Sands Missile Range, NM

Venu Siddapureddy and Darryl Bryk  
US Army RDECOM-TARDEC  
Warren, MI

10 Aug. 2011

**GVSETS**

Report Documentation Page			Form Approved OMB No. 0704-0188		
Public reporting burden for the collection of information is estimated to average 1 hour per response, including the time for reviewing instructions, searching existing data sources, gathering and maintaining the data needed, and completing and reviewing the collection of information. Send comments regarding this burden estimate or any other aspect of this collection of information, including suggestions for reducing this burden, to Washington Headquarters Services, Directorate for Information Operations and Reports, 1215 Jefferson Davis Highway, Suite 1204, Arlington VA 22202-4302. Respondents should be aware that notwithstanding any other provision of law, no person shall be subject to a penalty for failing to comply with a collection of information if it does not display a currently valid OMB control number.					
1. REPORT DATE <b>10 AUG 2011</b>		2. REPORT TYPE <b>N/A</b>		3. DATES COVERED <b>-</b>	
4. TITLE AND SUBTITLE <b>A Novel Approach for a Hostile Arms Fire Sensor</b>			5a. CONTRACT NUMBER		
			5b. GRANT NUMBER		
			5c. PROGRAM ELEMENT NUMBER		
6. AUTHOR(S) <b>Joseph Rudy Montoya; Jorge Melchor Venu Siddapureddy; Darryl Bryk</b>			5d. PROJECT NUMBER		
			5e. TASK NUMBER		
			5f. WORK UNIT NUMBER		
7. PERFORMING ORGANIZATION NAME(S) AND ADDRESS(ES) <b>US Army RDECOM-TARDEC 6501 E 11 Mile Rd Warren, MI 48397-5000, USA US Army Research Laboratory-SLAD White Sands Missile Range, NM, USA</b>			8. PERFORMING ORGANIZATION REPORT NUMBER <b>22203</b>		
9. SPONSORING/MONITORING AGENCY NAME(S) AND ADDRESS(ES) <b>US Army RDECOM-TARDEC 6501 E 11 Mile Rd Warren, MI 48397-5000, USA</b>			10. SPONSOR/MONITOR'S ACRONYM(S) <b>TACOM/TARDEC/RDECOM</b>		
			11. SPONSOR/MONITOR'S REPORT NUMBER(S) <b>22203</b>		
12. DISTRIBUTION/AVAILABILITY STATEMENT <b>Approved for public release, distribution unlimited</b>					
13. SUPPLEMENTARY NOTES <b>Presented at the 2011 NDIA Vehicles Systems Engineering and Technology Symposium 9-11 August 2011, Dearborn, Michigan, USA, The original document contains color images.</b>					
14. ABSTRACT					
15. SUBJECT TERMS					
16. SECURITY CLASSIFICATION OF:			17. LIMITATION OF ABSTRACT <b>SAR</b>	18. NUMBER OF PAGES <b>9</b>	19a. NAME OF RESPONSIBLE PERSON
a. REPORT <b>unclassified</b>	b. ABSTRACT <b>unclassified</b>	c. THIS PAGE <b>unclassified</b>			

# Issue and Objective

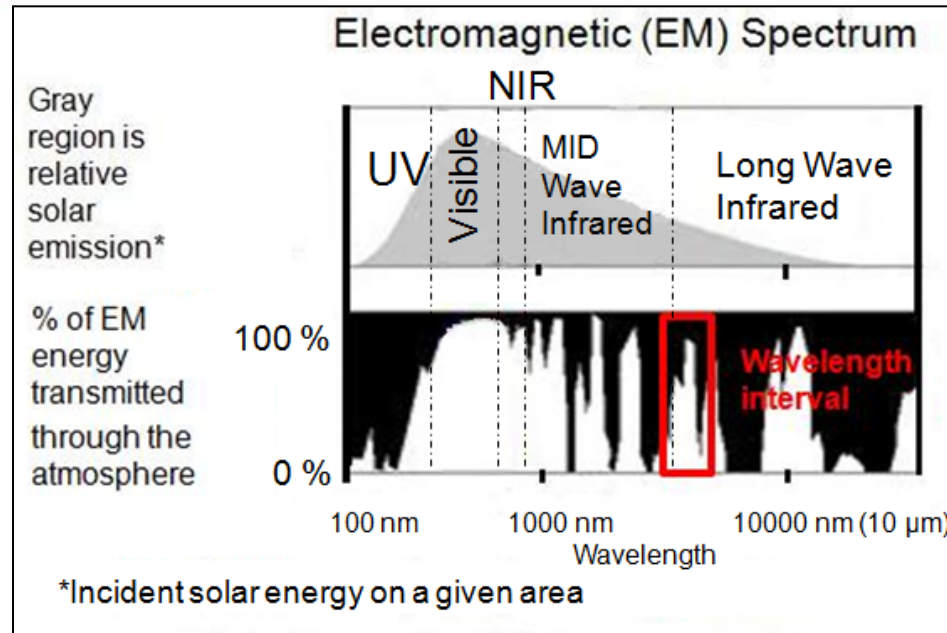
## Issue:

- Utilizing the multispectral properties of the electromagnetic spectrum , sensor methodology has been tested very successfully in detecting point of origin of various types of arms fire. In-theatre travel in caravans has drawn enemy fire with urban settings making it difficult to discern point of origin. This new multispectral methodology may overcome false alarm problems that can plague other types of sensors.

## Objective:

- Show multispectral approach.
- Example of a multispectral imaging system.

# Multispectral Defined



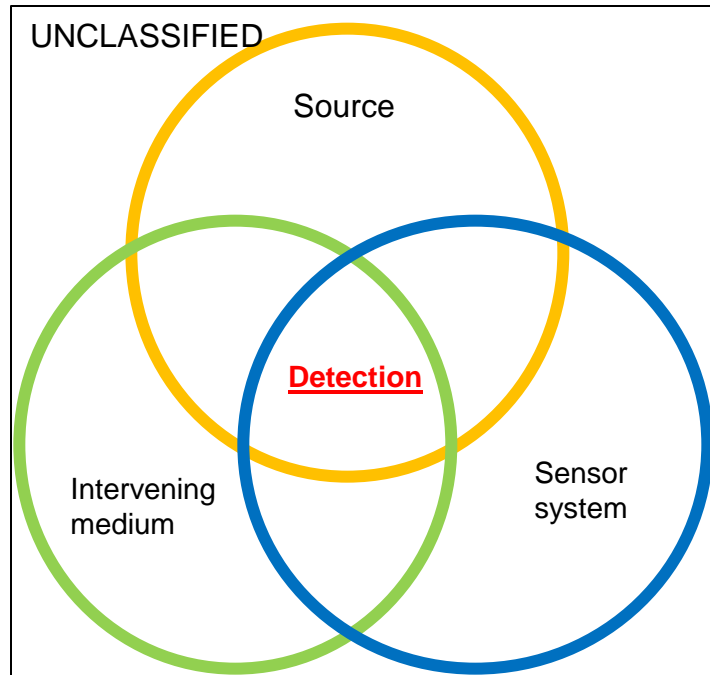
- The EM spectrum has been partitioned into general regions that have common characteristics, which are ultraviolet (UV), near-infrared (NIR), visible, mid-wave infrared (MWIR) and long wave infrared (LWIR).
- Multispectral is the use of multiple separate wavelength intervals. These wavelength intervals have characteristics that are wavelength dependent such as but not limited to solar emission and atmospheric transmission.
- Wavelength intervals can be in one or multiple EM regions.

# Multispectral Methodology for Detection

- Multispectral methodology is the exploitation of useful wavelength-dependent characteristics. This exploitation can be within one single or multiple EM regions.
- Each EM region has its own sensor technology and the use of multiple regions in a multispectral methodology will generally increase exploitation complexity.
- Solar emission, which is wavelength dependent, is the leading cause of false detection.
- False detection will be mitigated by the application of multispectral methodology.

Electromagnetic (EM) region	Transmission through medium	Sensor
Ultraviolet (UV)	Poor	<b>No solar emission observed</b>
Visible/ Near Infrared (NIR)	<b>Good</b>	<b>Low cost</b> , solar emission observed
Mid Wave Infrared (MWIR) and Long Wave Infrared (LWIR)	<b>Very Good</b>	Expensive, solar emission observed

# Detect Threat Using Multispectral Methodology



TRADE SPACE

**Source** is launch flash. The energy released or radiant intensity is wavelength dependent.

Transmission through **intervening medium** such as obscurants and atmosphere are wavelength dependent.

The spectral response of a **sensor system** is wavelength dependent.

Using the trade space including, source, intervening medium, and sensor system may provide a solution for detection of a threat launch event. For example, applying the multispectral methodology hostile fire.

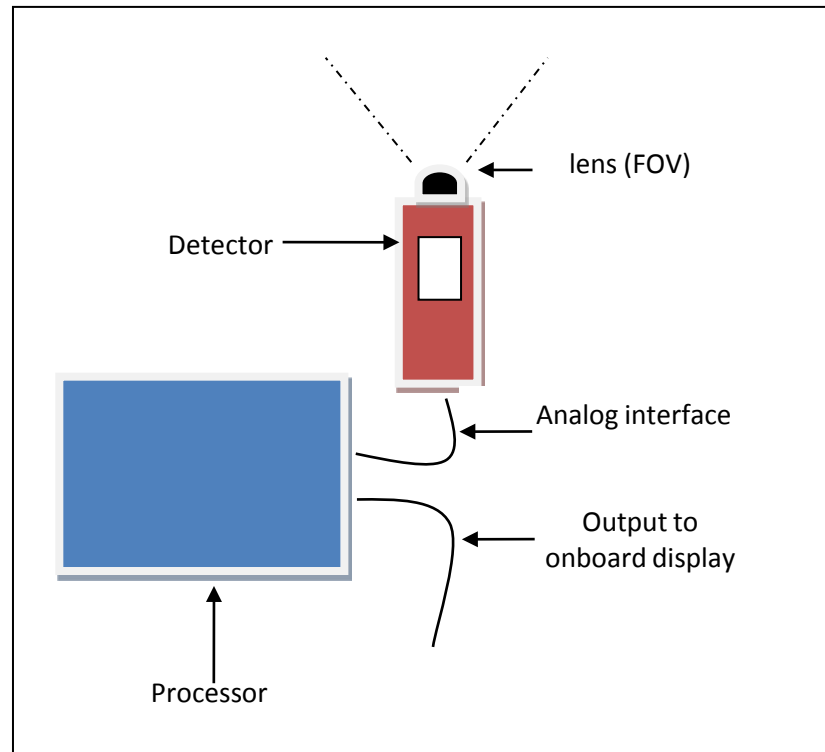
# Multispectral Imaging System

Typical parameters of a notional multispectral imaging system

- Processor module - 4 ft x 3 ft x 1 ft, weight 25lbs
- Sensor module - 3 ft x 1ft x 0.5ft, weight of 5lbs.

## •ISSUES:

- ICD – Communication protocols
- Size, weight and power (typical power usage is <5 amps)
- Multispectral system may need large data storage, extensive data processing capability.





# Multispectral Device Slewing a Tracker

**VEA**  
VEHICLE ELECTRONICS AND ARCHITECTURE

Tracking device slews to follow a lit match (target)





# Sensory System Integration Issues



## Vehicle platform and system issues:

- Sensor system merits
- Technology readiness level (TRL)
- MIL standards certification
- Mechanical, electrical, and data interfaces
- Threat messages with range, elevation, and azimuth
- System interface with Remote Weapons Station
- Processing requirements
- System built using open data architecture standards, modular system configuration
- Development kit for ease of integration and testing

# Conclusion

- Long range detection
- False alarm rate is low
- Faster detection time than an acoustic signal due to detection in the electromagnetic spectrum
- Production price is less than current fielded systems
- Ease of data integration to vehicular system due to open system development
- Modularity in design will allow configuration to many vehicle platforms

